

MSC1157

Speaker Drive Amplifier

GENERAL DESCRIPTION

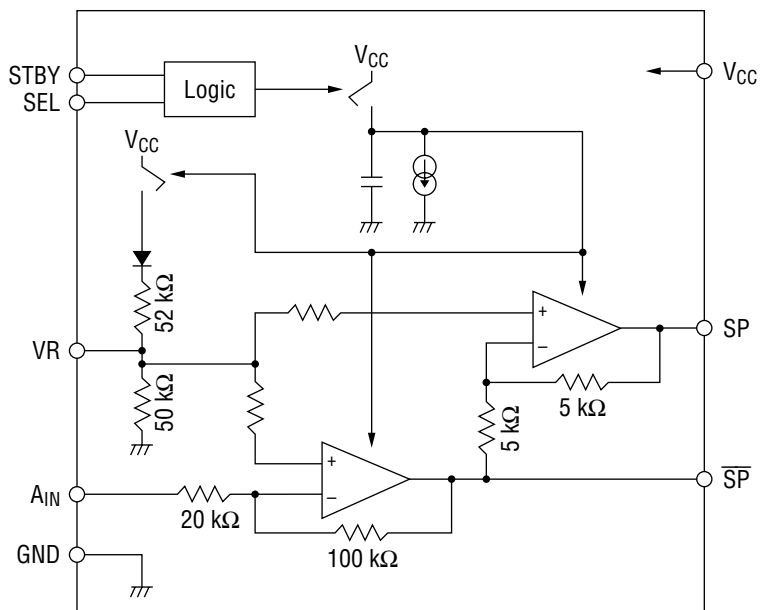
The MSC1157, designed specifically to operate at a low voltage with low current consumption, is a power amplifier developed for driving a speaker for a voice IC.

The voltage gains can be adjusted over a range of up to ten. The differential output can directly drive a speaker without any output coupling capacitors. The MSC 1157, because of its ability to stand by, is ideally suitable for portable equipment applications powered by a battery.

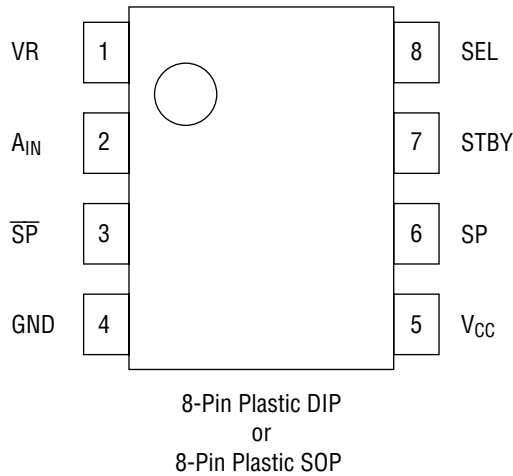
FEATURES

- Low voltage operation : 2.0 to 6.0 V (Single power supply)
- Low current dissipation : 1.6mA without load (typ.)
- Standby function : Current dissipation less than 1 μ A in standby
- High output current : 350mA peak
- Differential outputs : A speaker can be directly connected between differential outputs.
- Adjustable gain : Gain can be adjusted by use of an external resistor.
- Package options:
 - 8-pin plastic DIP (DIP8-P-300-2.54) (Product name : MSC1157RS)
 - 8-pin plastic SOP (SOP8-P-250-1.27-K) (Product name : MSC1157MS-K)
 - Chip

BLOCK DIAGRAM



PIN CONFIGURATION (TOP VIEW)



PIN DESCRIPTIONS

| Pin | Symbol | Type | Description | | | | | | | | | | | | | | | | | | | | | | | | |
|-------|-----------------|--------------------|---|-----|------|--------|---|---|-----------|---|---------|-------|-----------|---|---|---------|---|-----------|-------|-----------|-------|---|-----------|---|-----------|-------|--------------------|
| 5 | V _{CC} | — | Power supply pin. | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | GND | — | Ground pin. | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | A _{IN} | I | Signal input pin for analog signal inputs, etc. | | | | | | | | | | | | | | | | | | | | | | | | |
| 7, 8 | STBY, SEL | I | <p>Digital input pins. Setting these pins configures the standby status. See the table below for how to set the pins.</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>SEL</th> <th>STBY</th> <th>Status</th> </tr> </thead> <tbody> <tr> <td rowspan="3">0</td> <td>0</td> <td>Operation</td> </tr> <tr> <td>1</td> <td>Standby</td> </tr> <tr> <td>Clock</td> <td>Operation</td> </tr> <tr> <td rowspan="3">1</td> <td>0</td> <td>Standby</td> </tr> <tr> <td>1</td> <td>Operation</td> </tr> <tr> <td>Clock</td> <td>Operation</td> </tr> <tr> <td rowspan="3">Clock</td> <td>0</td> <td>Operation</td> </tr> <tr> <td>1</td> <td>Operation</td> </tr> <tr> <td>Clock</td> <td>Unstable Operation</td> </tr> </tbody> </table> <p>Applying a clock between 32kHz and 4MHz to either the STBY or the SEL pin leads the IC to operation status regardless of the status set at the other pin. Applying clocks to both of the pins at the same time may cause malfunction.</p> <p><u>Refer to the section, RECOMMENDED OPERATING CONDITIONS since clock frequencies are changed by setting the SEL pin.</u></p> | SEL | STBY | Status | 0 | 0 | Operation | 1 | Standby | Clock | Operation | 1 | 0 | Standby | 1 | Operation | Clock | Operation | Clock | 0 | Operation | 1 | Operation | Clock | Unstable Operation |
| SEL | STBY | Status | | | | | | | | | | | | | | | | | | | | | | | | | |
| 0 | 0 | Operation | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 1 | Standby | | | | | | | | | | | | | | | | | | | | | | | | | |
| | Clock | Operation | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | 0 | Standby | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 1 | Operation | | | | | | | | | | | | | | | | | | | | | | | | | |
| | Clock | Operation | | | | | | | | | | | | | | | | | | | | | | | | | |
| Clock | 0 | Operation | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 1 | Operation | | | | | | | | | | | | | | | | | | | | | | | | | |
| | Clock | Unstable Operation | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | VR | 0 | <p>Bias output pin for internal circuits. This pin is at GND potential during standby. Connecting a capacitor between VR and the GND pin reduces the pop-up noise at power on and improves the ripple elimination ratio.</p> | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | SP-bar | 0 | Speaker output pin. This pin outputs a negative phase with respect to the input signal. | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | SP | 0 | Speaker output pin. This pin outputs a positive phase with respect to the input signal. | | | | | | | | | | | | | | | | | | | | | | | | |

ABSOLUTE MAXIMUM RATINGS

| Parameter | Symbol | Condition | Rating | Unit | Remark |
|------------------------|------------|------------------------|----------------------|------------------|------------------------|
| Power Supply Voltage | V_{CC} | $T_a=25^\circ\text{C}$ | -0.3 to +6.5 | V | V_{CC} |
| Input Voltage | V_{IN} | $T_a=25^\circ\text{C}$ | -0.3 to $V_{CC}+0.3$ | V | STBY A_{IN} , SEL |
| Maximum Output Current | I_{OMAX} | $T_a=25^\circ\text{C}$ | (*1) ± 400 | mA | SP, \overline{SP} |
| Power Dissipation | P_D | $T_a=25^\circ\text{C}$ | 470 | mW | DIP type |
| | | | 400 | mW | SOP type |
| Junction Temperature | T_{jMAX} | — | 125 | $^\circ\text{C}$ | Chip |
| Storage Temperature | T_{STG} | — | -55 to +150 | $^\circ\text{C}$ | |

*1 Avoid shorting the output pins (SP and \overline{SP}) to V_{CC} or GND because the IC may be damaged.

RECOMMENDED OPERATING CONDITIONS

| Parameter | Symbol | Condition | Min. | Max. | Unit |
|-------------------------------|------------|---|--------------|--------------|------------------|
| Power Supply Voltage | V_{CC} | — | 2.0 | 6.0 | V |
| Load Impedance (*2) | R_L | — | 8.0 | — | Ω |
| Peak Load Current | I_{O-P} | — | — | 350 | mA |
| "H" Input Voltage | V_{IH} | For STBY and SEL pins | 0.7 V_{CC} | — | V |
| "L" Input Voltage | V_{IL} | | — | 0.3 V_{CC} | V |
| STBY Operating Frequency (*3) | f_{STBY} | SEL = "L" At clock input $V_{CC} \geq 2.4\text{ V}$ | 32 k | 4.096 M | Hz |
| | | SEL = "H" At clock input $V_{CC} \geq 2.4\text{ V}$ | 32 k | 1 M | |
| Operating Temperature | T_{op} | — | -20 | +70 | $^\circ\text{C}$ |

*2 A speaker of 8 Ω (standard) or more should be used.

*3 The input of clocks may cause a little noise in output waveforms.

It is recommended to input the DC voltage to improve voice quality.

ELECTRICAL CHARACTERISTICS

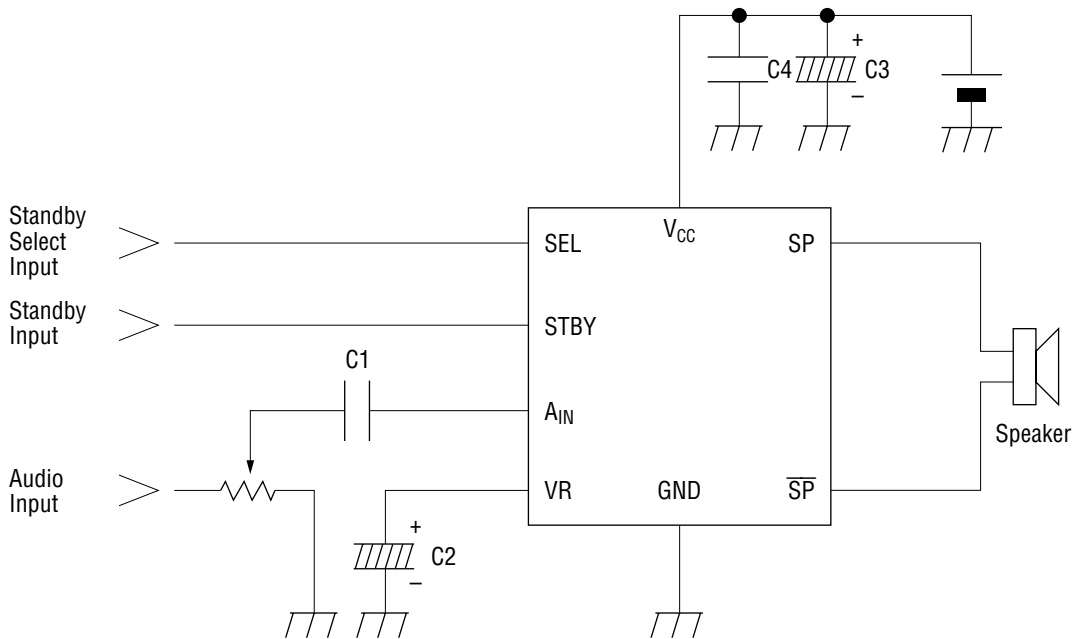
Unless otherwise specified, Ta=25°C, VCC=2 to 6 V

| Parameter | Symbol | Condition | Min. | Typ. | Max. | Unit | |
|----------------------------------|-------------------|---|-----------------------|-----------------------|-------|------|---|
| A _{IN} Input Resistance | R _{IN} | — | 14 | 20 | 26 | kΩ | |
| Voltage Gain | A _{V1} | A _{IN} →SP | 13.44 | 14 | 14.49 | dB | |
| | A _{V2} | SP→SP | -1.94 | 0 | +1.58 | | |
| | A _{V3} | A _{IN} →(Between SP-SP) | 19.46 | 20 | 20.51 | | |
| Output Power | P _{OUT1} | V _{CC} =3 V, f=1 kHz R _L =8 Ω, THD≥10% | 100 | 178 | — | mW | |
| | P _{OUT2} | V _{CC} =6 V, f=1 kHz R _L =32 Ω, THD≥10% | 300 | 440 | — | mW | |
| Total Harmonic Distortion | THD1 | V _{CC} =3 V, R _L =8 Ω f=1 kHz, P _{OUT} =45 mW | — | 1.2 | — | % | |
| | THD2 | V _{CC} =6 V, R _L =32 Ω f=1 kHz, P _{OUT} =125 mW | — | 0.37 | — | % | |
| Ripple Elimination Ratio | RR | f=1 kHz, C2=4.7 μF | 30 | 43 | — | dB | |
| Output DC Voltage (*4) | V _O | In no signal state | V _{CC} =2 V | 0.53 | 0.65 | 0.77 | V |
| | | V _{CC} =6 V | 2.49 | 2.61 | 2.73 | | |
| Output Offset Voltage | ΔV _O | Between SP-SP | — | — | ±30 | mV | |
| Output "H" Voltage | V _{OH} | A _{IN} =V _{CC} or GND I _{OUT} =-100 mA | V _{CC} -1.15 | V _{CC} -1.04 | — | V | |
| Output "L" Voltage | V _{OL} | A _{IN} =V _{CC} or GND I _{OUT} =100 mA | — | 0.17 | 0.3 | V | |
| STBY, SEL Input Current | I _{IH} | V _I =V _{CC} | — | — | ±0.1 | μA | |
| | I _{IL} | V _I =GND | — | — | ±0.1 | μA | |
| VR Equivalent Resistance | R _{VR} | — | 18 | 25 | 32 | kΩ | |
| Circuit Current During Operation | I _{CC} | V _{CC} =6 V, R _L =∞ | 1.1 | 1.6 | 2.4 | mA | |
| Circuit Current During Standby | I _{CCS} | — | — | — | 1.0 | μA | |

*4 The typical value of the output voltage in no signal state is determined from the following equation.

$$V_O = (V_{CC} - 0.67) \frac{50 \text{ k}\Omega}{50 \text{ k}\Omega + 52 \text{ k}\Omega}$$

APPLICATION CIRCUIT



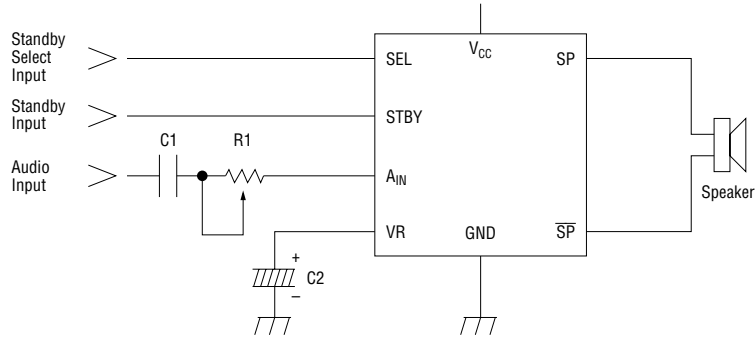
- If parasitic capacitance of 60pF or more exists between GND and the speaker output pin \overline{SP} or \overline{SP} , oscillation may occur. Implement the circuit mount design so as to be less than 60pF.
- C1 is the AC coupling capacitor. Cutoff frequency f_c on the low frequency side is determined by the following equation. Choose a value of C1 according to the bandwidth.

$$f_c = \frac{1}{2 \times \pi \times C1 \times 20k} \text{ (Hz)}$$

- Choose a value of C2 that is 80 to 100 times as large as that of C1.
- When the standby function is not used, connect the pins STBY and SEL to V_{CC} or GND.
- It is recommended that the capacitor C4 (approximately 0.1 μ F) having better high frequency characteristics and the capacitor C3 (approximately 10 μ F) be placed between the pins V_{CC} and GND.

GAIN ADJUSTMENT

1. Gain Adjustment Using Input Resistance (This approach allows gain adjustment with fewer external components)



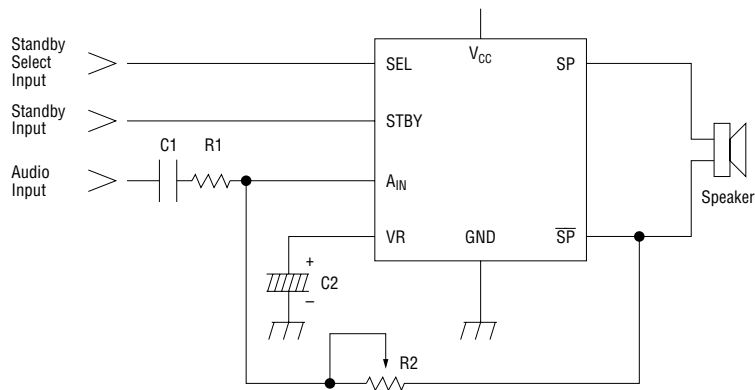
- Cutoff frequency f_c on the low frequency side is determined from the equation:

$$f_c \doteq \frac{1}{2 \times \pi \times C1 \times (R1 + 20k)} \text{ (Hz)}$$

- Voltage gain A_{V1} is determined from the equation:

$$A_{V1} \doteq \frac{100k}{R1 + 20k} \text{ (V/V)}$$

2. Gain Adjustment Using Feedback Resistance (This approach has the advantage over the above approach (less noise approach), but the number of components is increased)



- Cutoff frequency f_c on the low frequency side is determined from the equation:

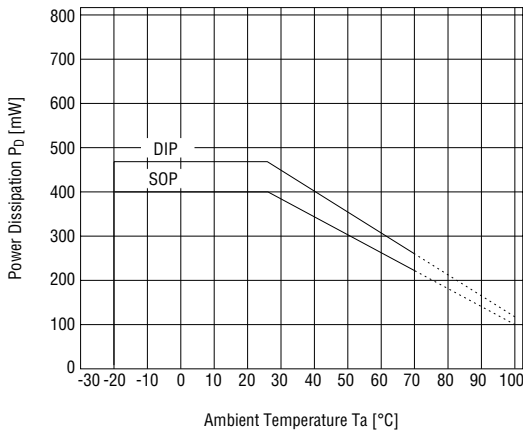
$$f_c \doteq \frac{1}{2 \times \pi \times C1 \times Z_{in}} \text{ (Hz)} \quad Z_{in} \doteq R1 + \frac{R2 \times 20k}{R2 + 120k} \text{ (\Omega)}$$

- Voltage gain A_{V1} is determined from the equation:

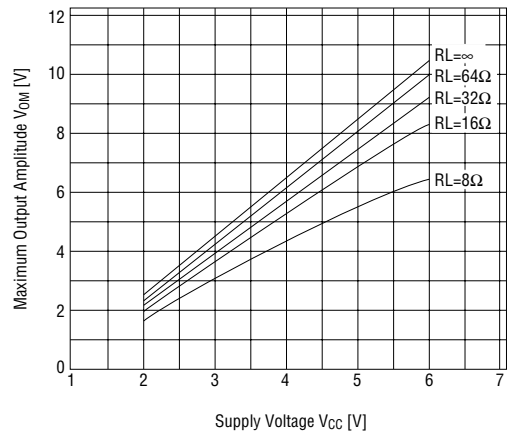
$$A_{V1} \doteq \frac{5}{1 + \frac{R1}{20k} + \frac{6 \times R1}{R2}} \text{ (V/V)}$$

OPERATING CHARACTERISTICS

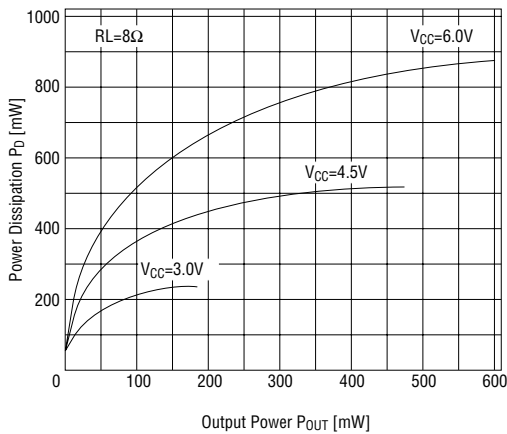
Power Dissipation vs. Ambient Temperature



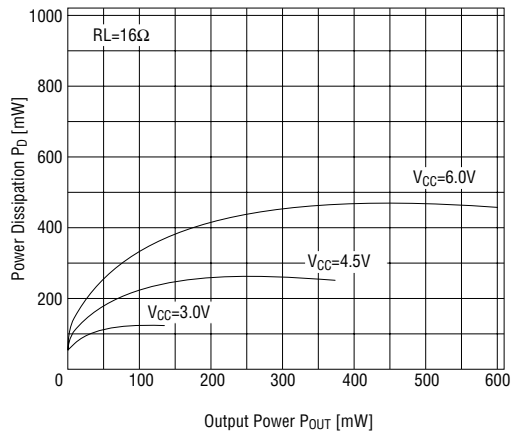
Maximum Output Amplitude vs. Voltage Supply



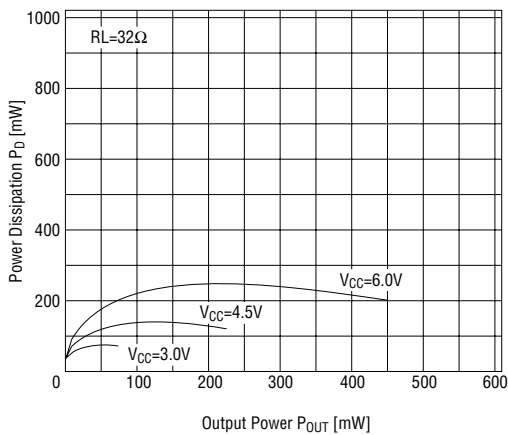
Power Dissipation vs. Output Power



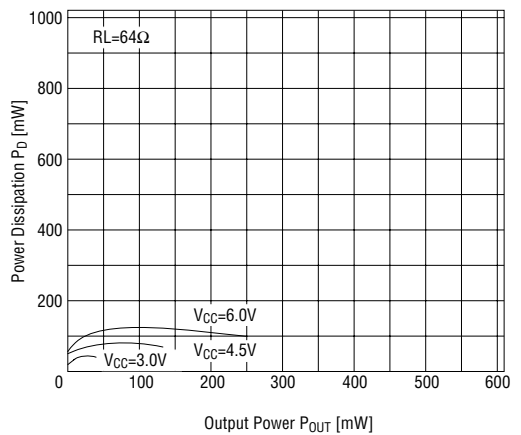
Power Dissipation vs. Output Power



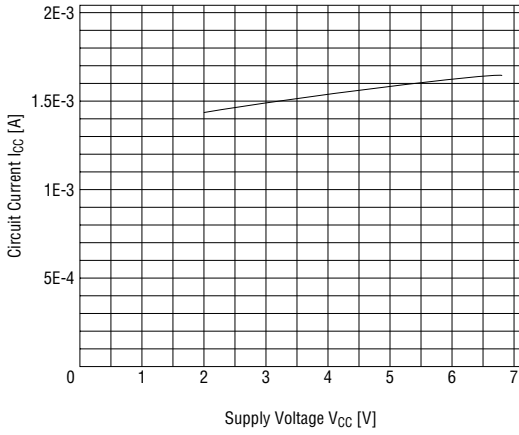
Power Dissipation vs. Output Power



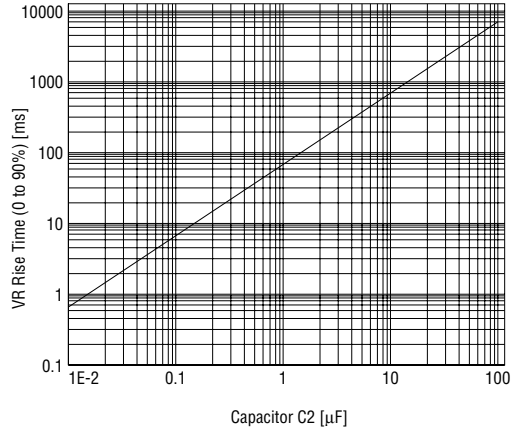
Power Dissipation vs. Output Power



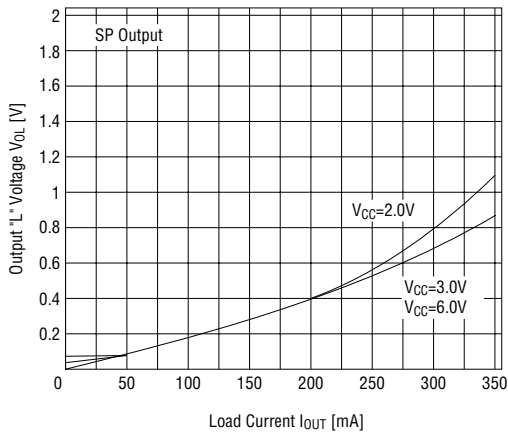
Circuit Current vs. Voltage Supply



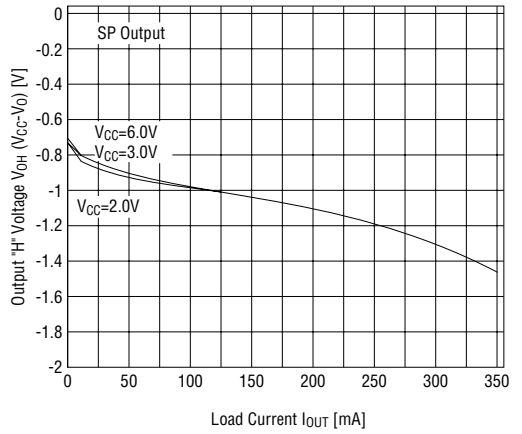
VR Rise Time vs. Capacitor Value (C2)



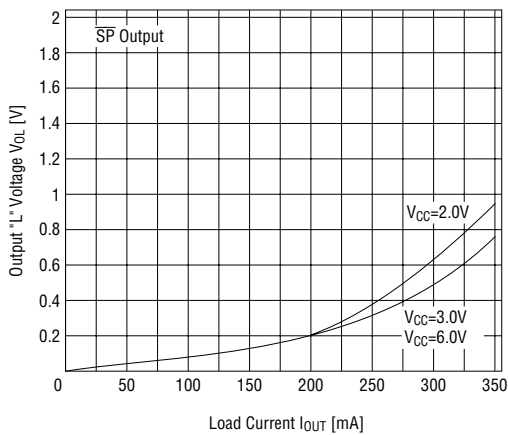
Output Voltage vs. Load Current



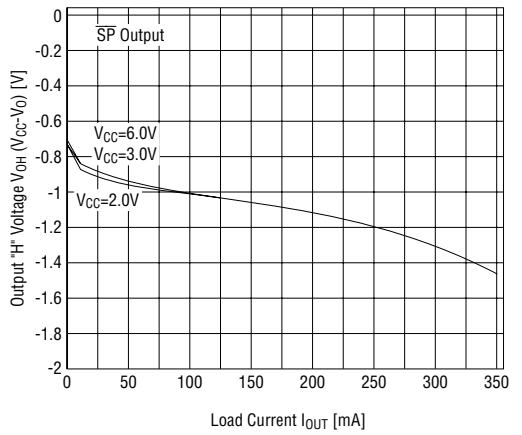
Output Voltage vs. Load Current

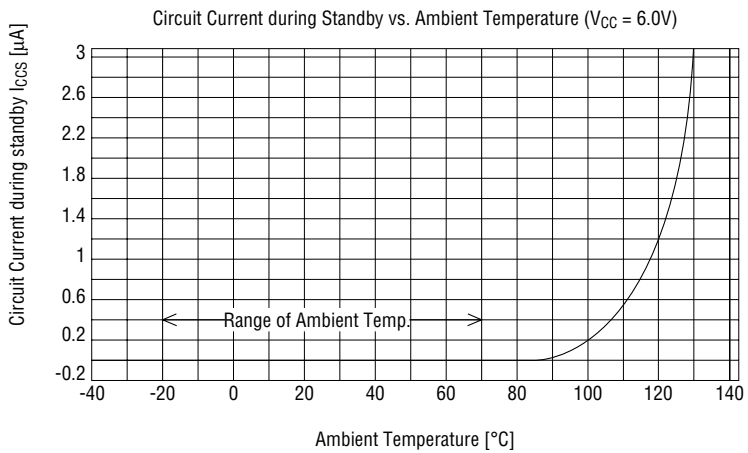
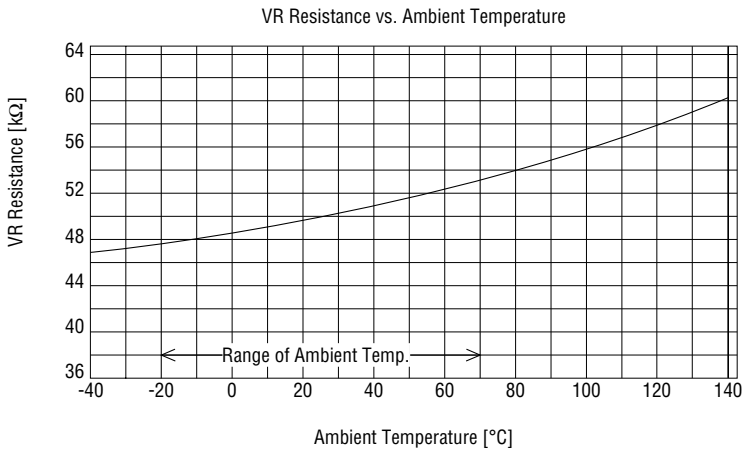
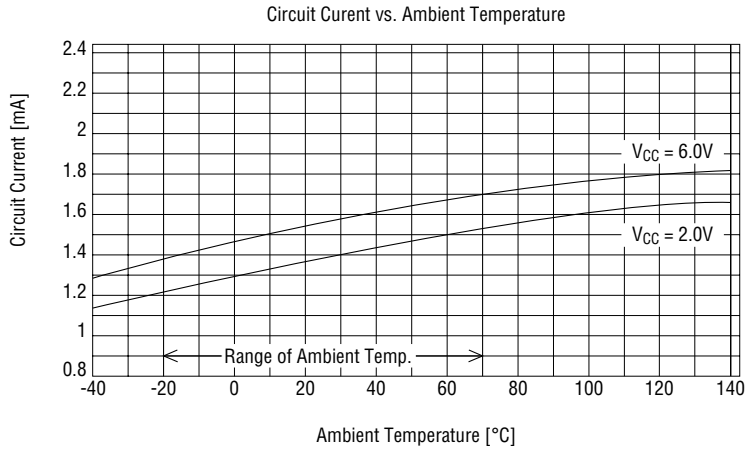


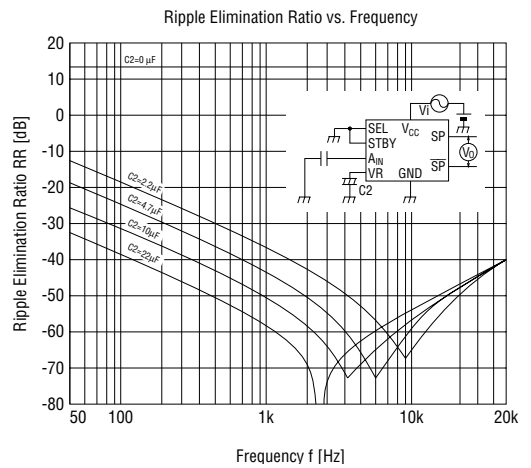
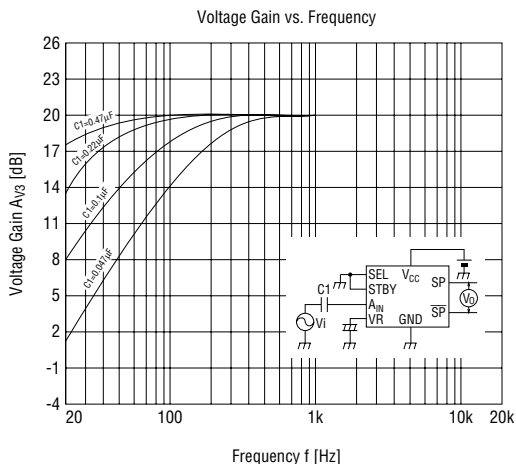
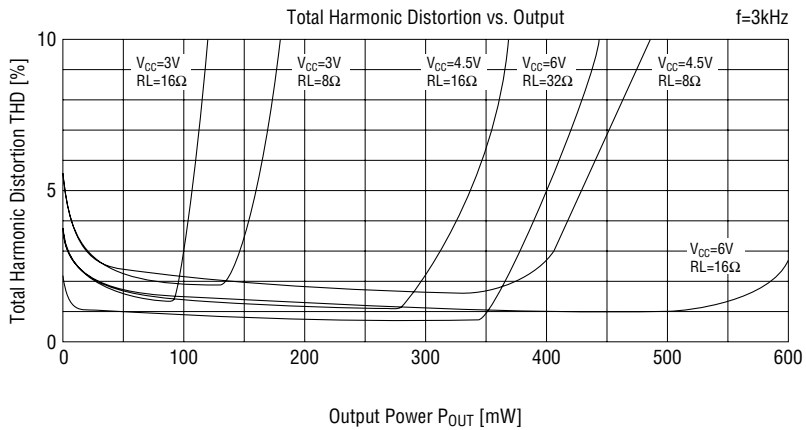
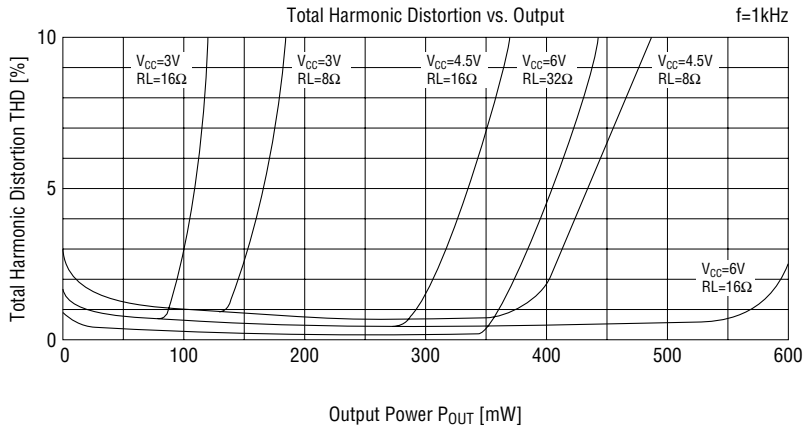
Output Voltage vs. Load Current



Output Voltage vs. Load Current



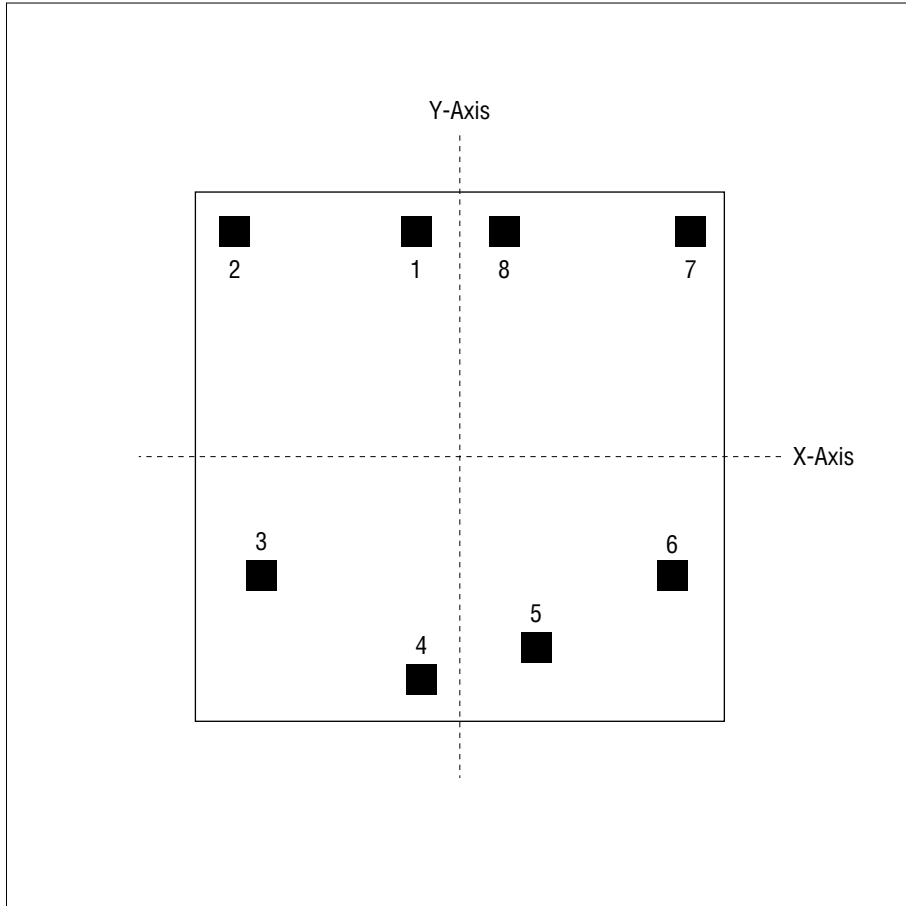




PAD CONFIGURATION

Pad Layout

Chip size : X=2.3mm, Y=2.4mm
 Chip thickness : 350±30µm
 Pad size (PV aperture) : 110×110µm
 Substrate potential : GND
 Pad location diagram



Pad Coordinates

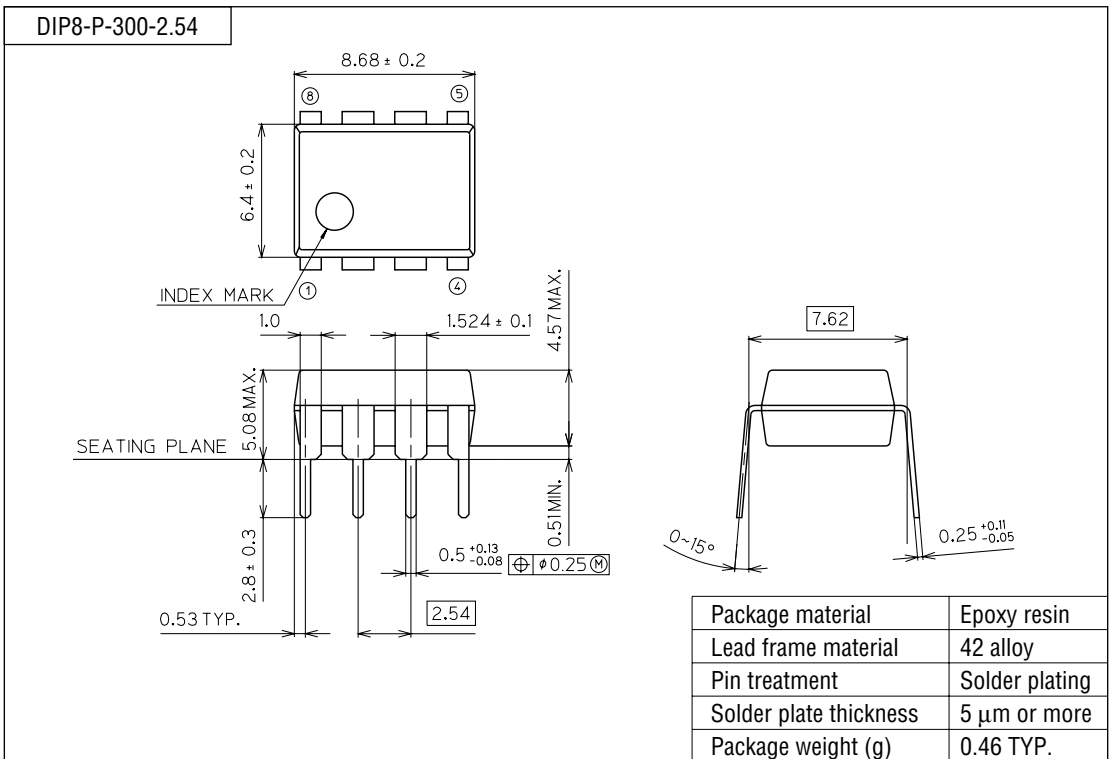
(Chip center is located at X=0 and Y=0.)

(Unit: µm)

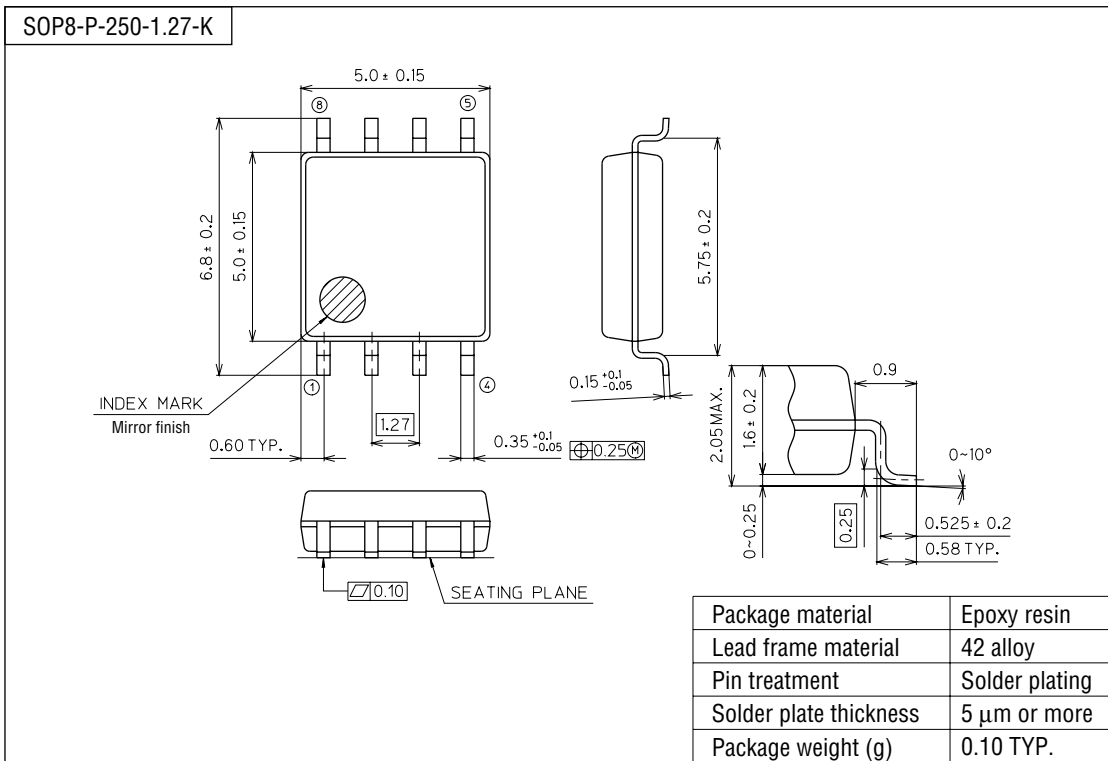
| Pad No. | Pad Name | X-AXIS | Y-AXIS |
|---------|-----------------|--------|--------|
| 1 | VR | -133 | 1035 |
| 2 | A _{IN} | -985 | 1035 |
| 3 | SP | -950 | -263 |
| 4 | GND | -180 | -1027 |
| 5 | V _{CC} | 240 | -914 |
| 6 | SP | 950 | -263 |
| 7 | STBY | 985 | 1035 |
| 8 | SEL | 159 | 1035 |

PACKAGE DIMENSIONS

(Unit : mm)



(Unit : mm)



Notes for Mounting the Surface Mount Type Package

The SOP, QFP, TSOP, TQFP, LQFP, SOJ, QFJ (PLCC), SHP, and BGA are surface mount type packages, which are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact Oki's responsible sales person on the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

NOTICE

1. The information contained herein can change without notice owing to product and/or technical improvements. Before using the product, please make sure that the information being referred to is up-to-date.
2. The outline of action and examples for application circuits described herein have been chosen as an explanation for the standard action and performance of the product. When planning to use the product, please ensure that the external conditions are reflected in the actual circuit, assembly, and program designs.
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